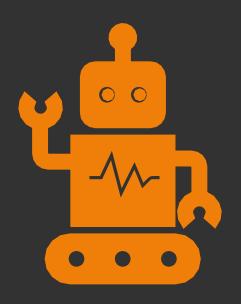


# Universidad Tecnológica Nacional Facultad Regional Paraná Inglés 1 2020

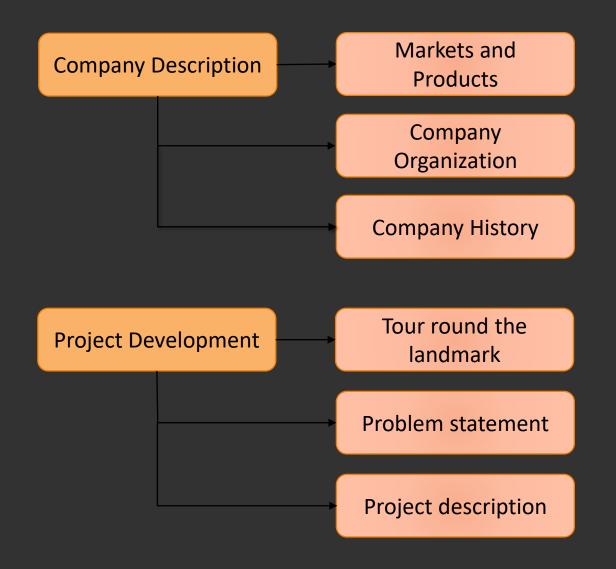


# Robotic Environment

ING. ESCOBAR GABRIEL

ING. ESPINDOLA AGUSTÍN

## Presentation Map





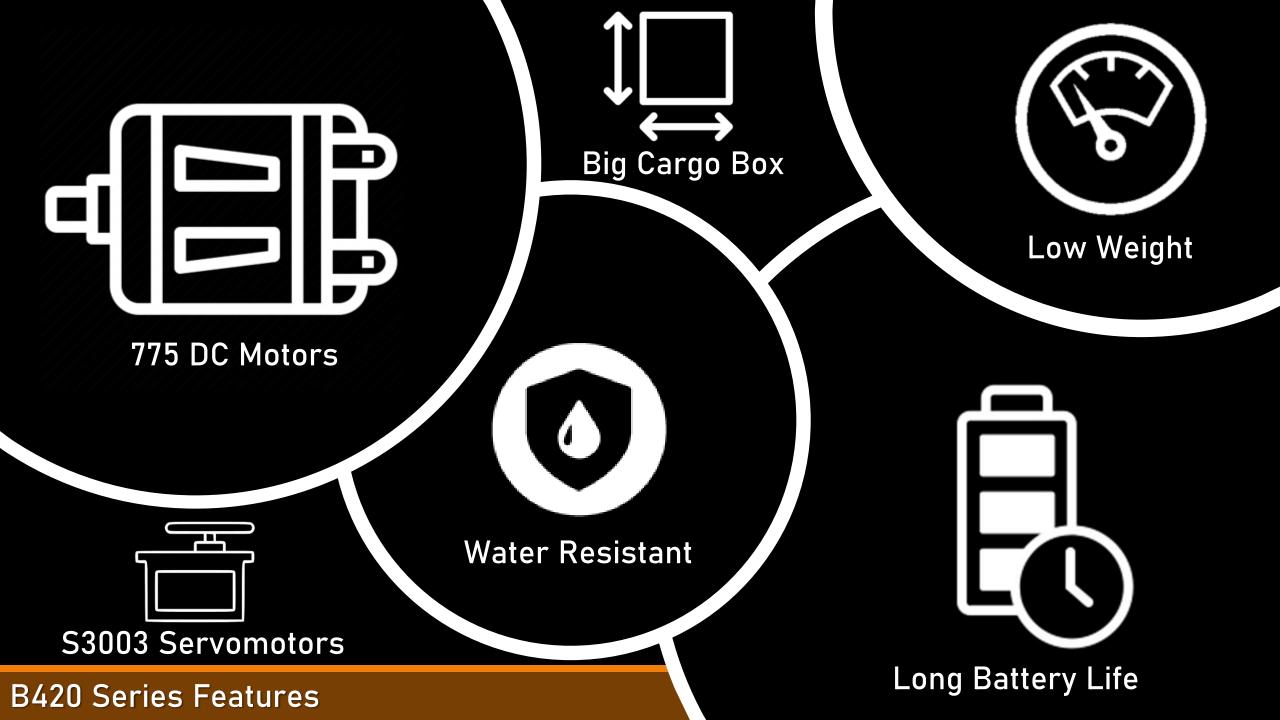
# Markets and Products



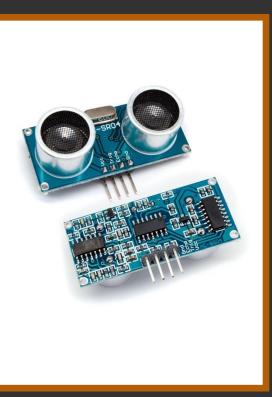
 Different lines specialized for all kinds of terrains.

- Accessible.
- Easy to implement.
- Relatively simple.
- Efficient.
- Low maintenance.





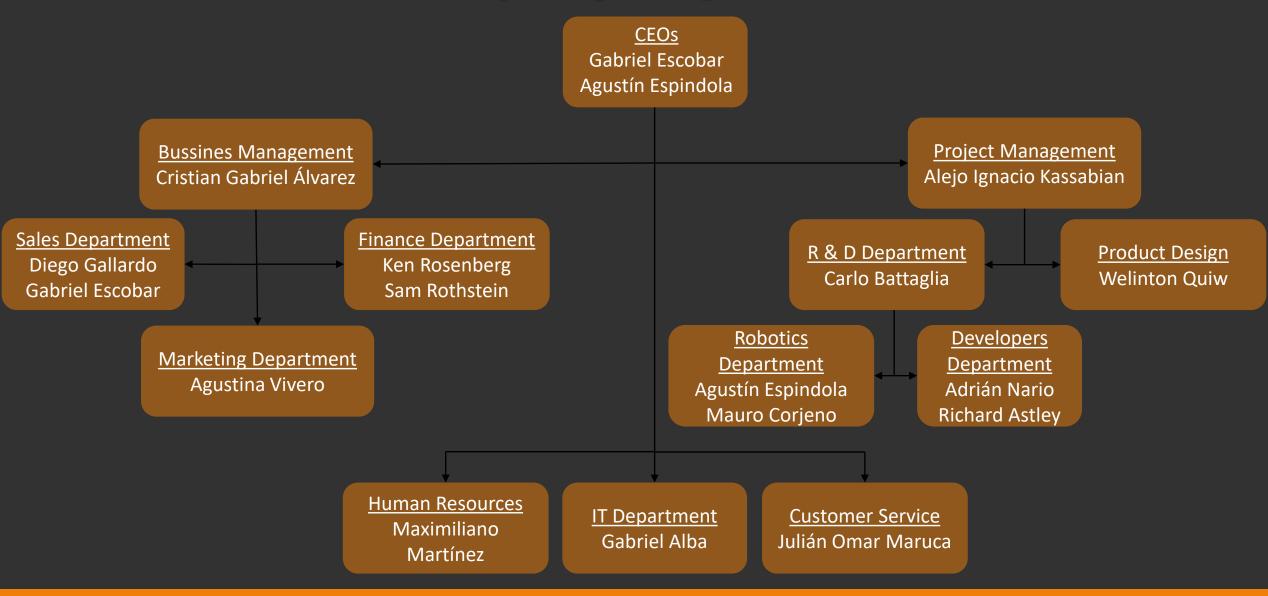




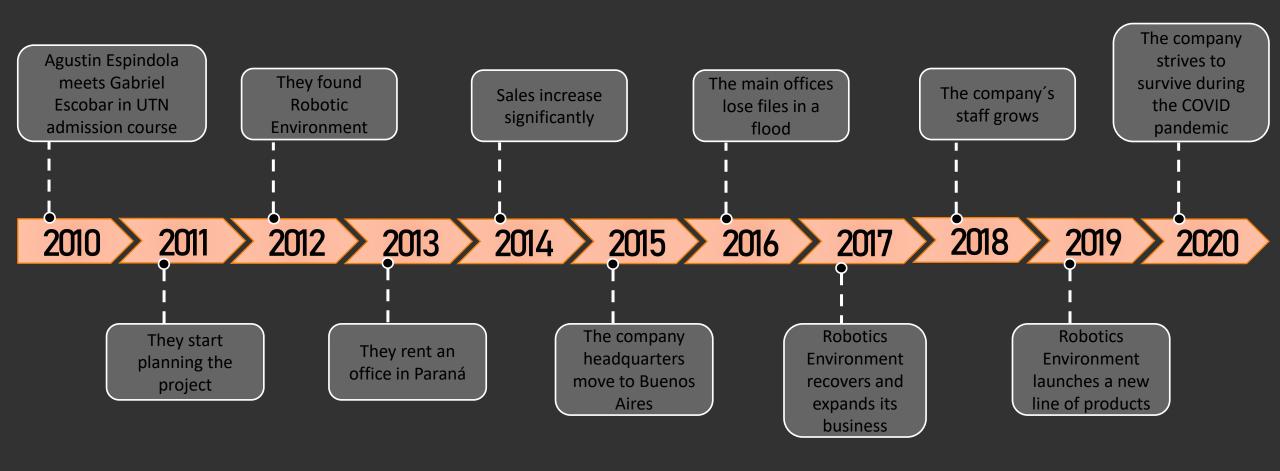
#### How it works

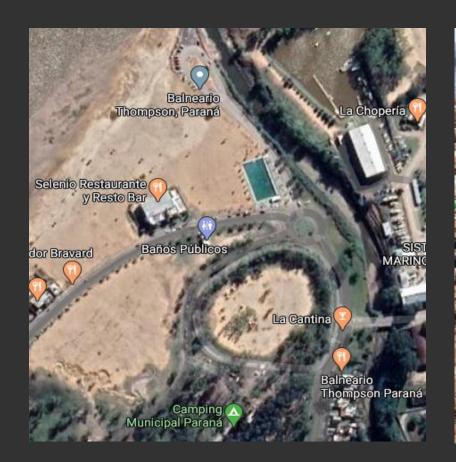
- The control is handled entirely with a simple Arduino Uno equipped with a L298P motor control shield.
- It makes use of a HC-SR04 ultrasonic sensor in the front side to detect objects in its way and send a signal to the frontal lift.

#### Company organization

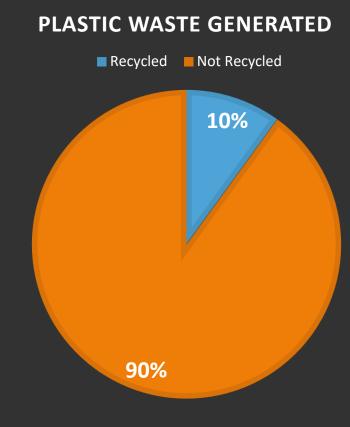


#### Company History - The Timeline









## **Problem Description**





#### **Project Description**

#### Stage I:

Our team tries to cover certain areas: The geographical study of different regions and its climates, the financial area, and the product manufacture.

Stage II: 1111 **Key points** Climatic Creative Geographic research process analysis **Training** Logical Economic estimation programming

#### **Project Description**

#### **Contingency Plan**:

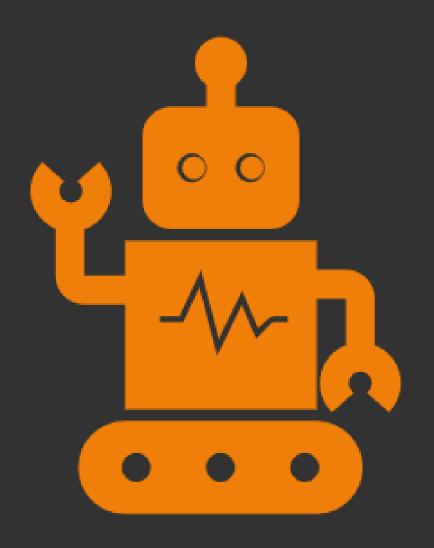


☐ Erratic power outages.



☐ Adverse climate during field work





## Company contact

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